

A First Embodiment of the PID Autotuning System of the Present Invention

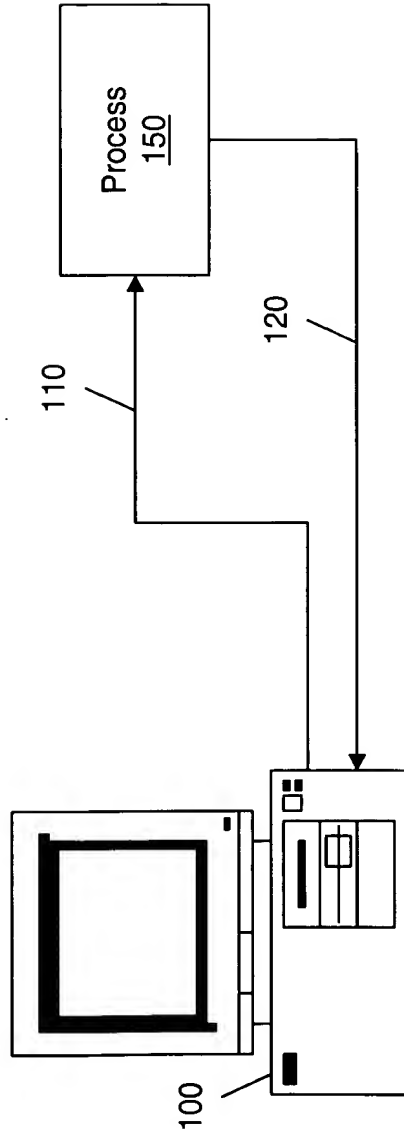


Figure 1A

A Second Embodiment of the PID Autotuning System of the Present Invention

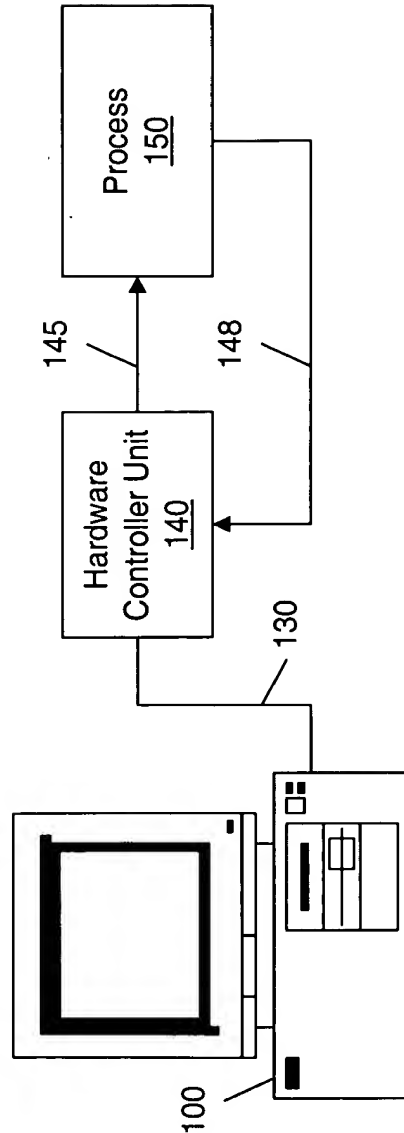
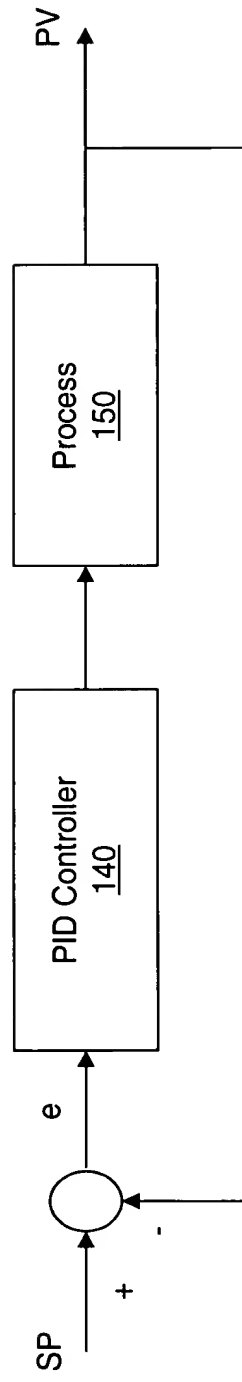


Figure 1B

000217 26897460



PID Control Loop
200

Figure 2

00021" 26891/60

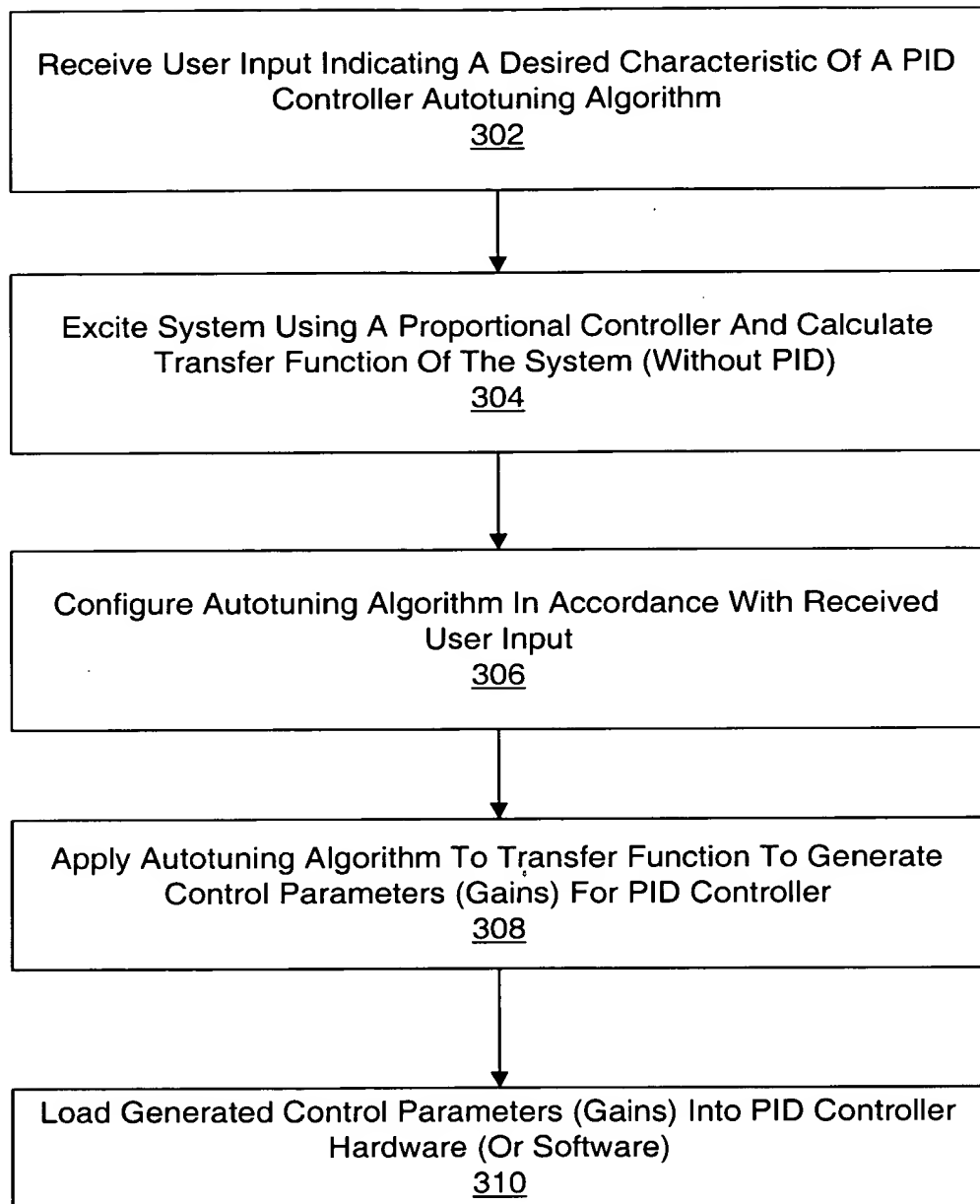


Figure 3

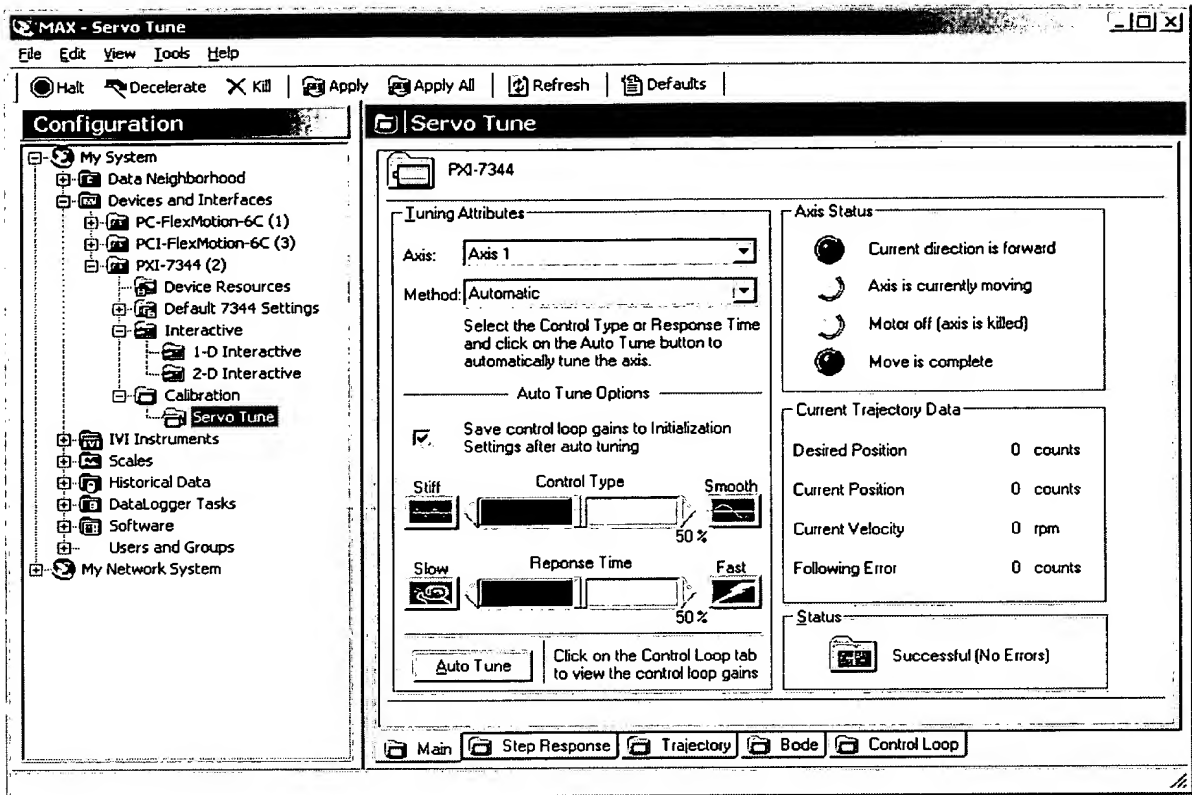


Figure 4A

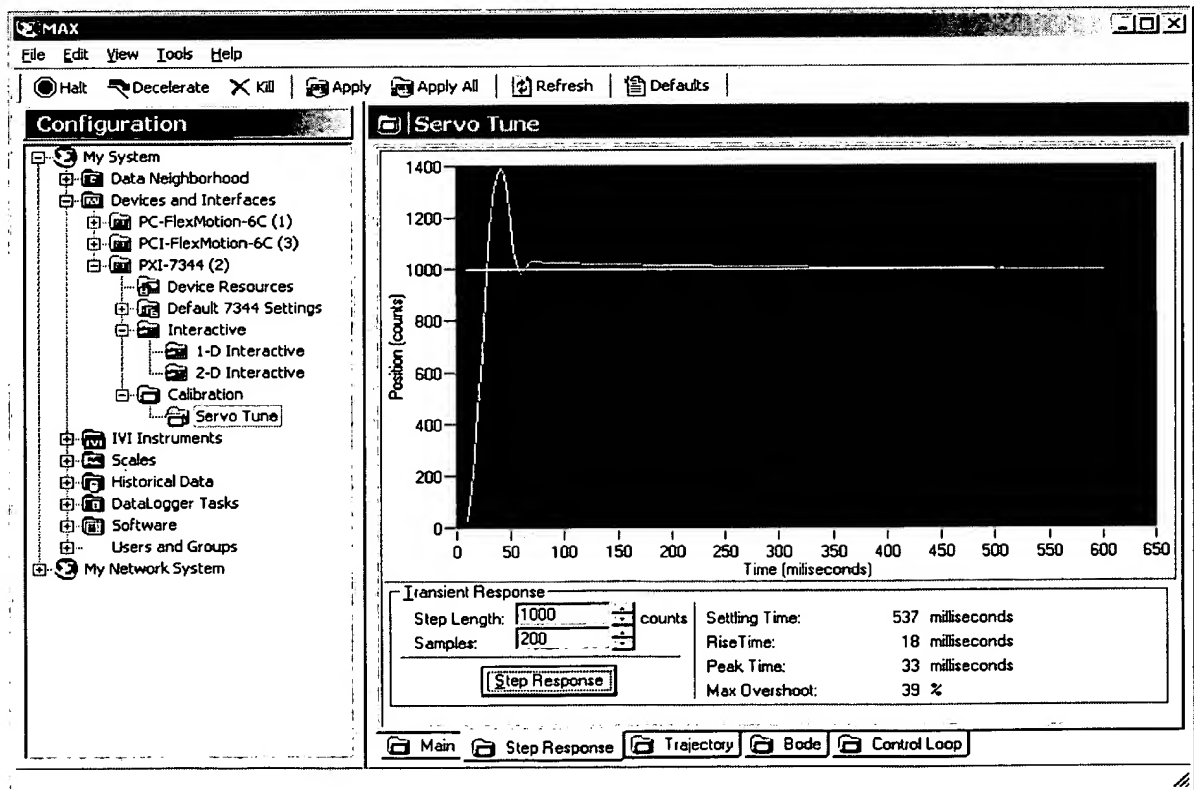


Figure 4B

09715892 " 112000

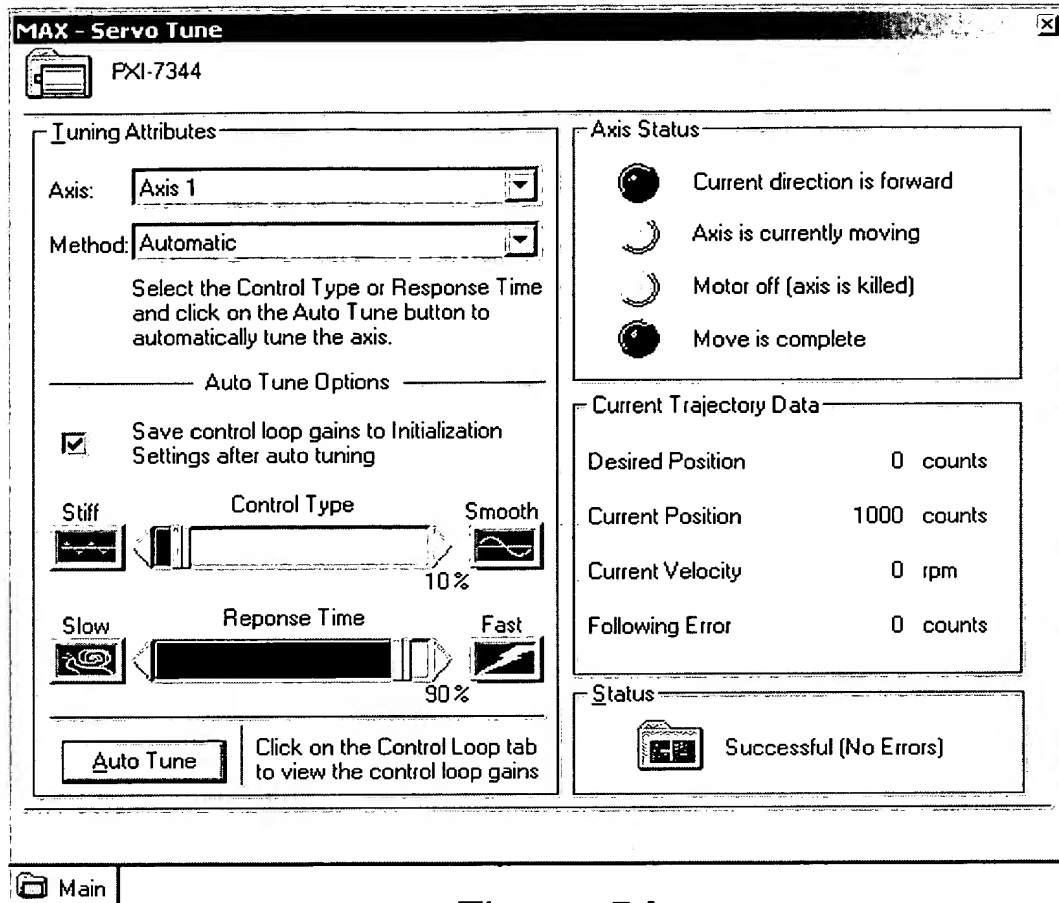


Figure 5A

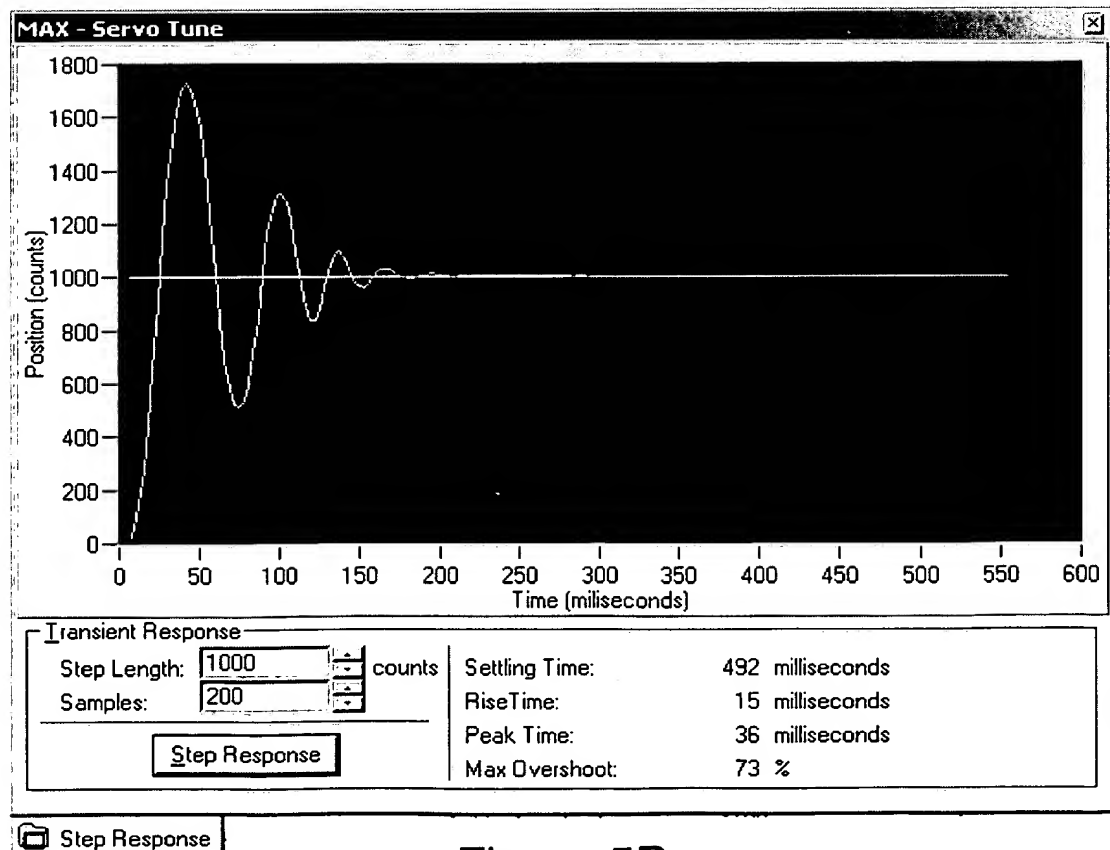


Figure 5B

000211 25891460

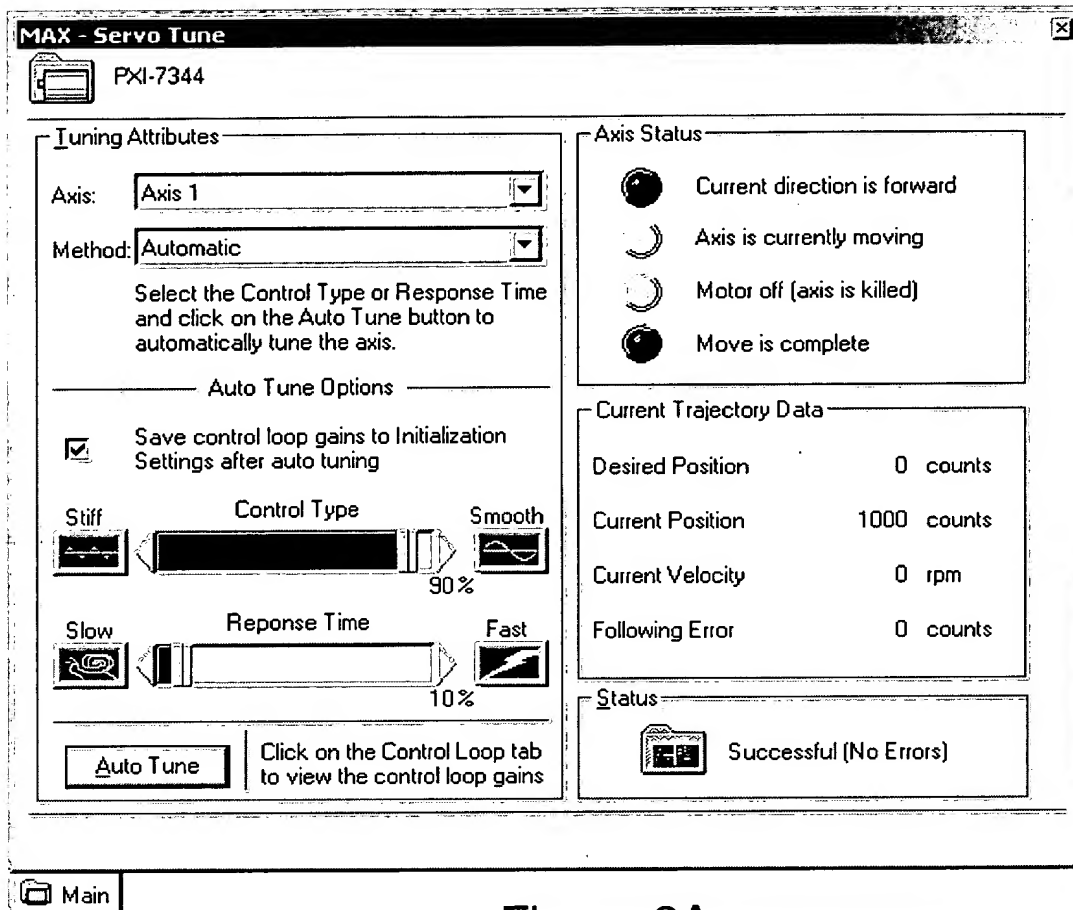


Figure 6A

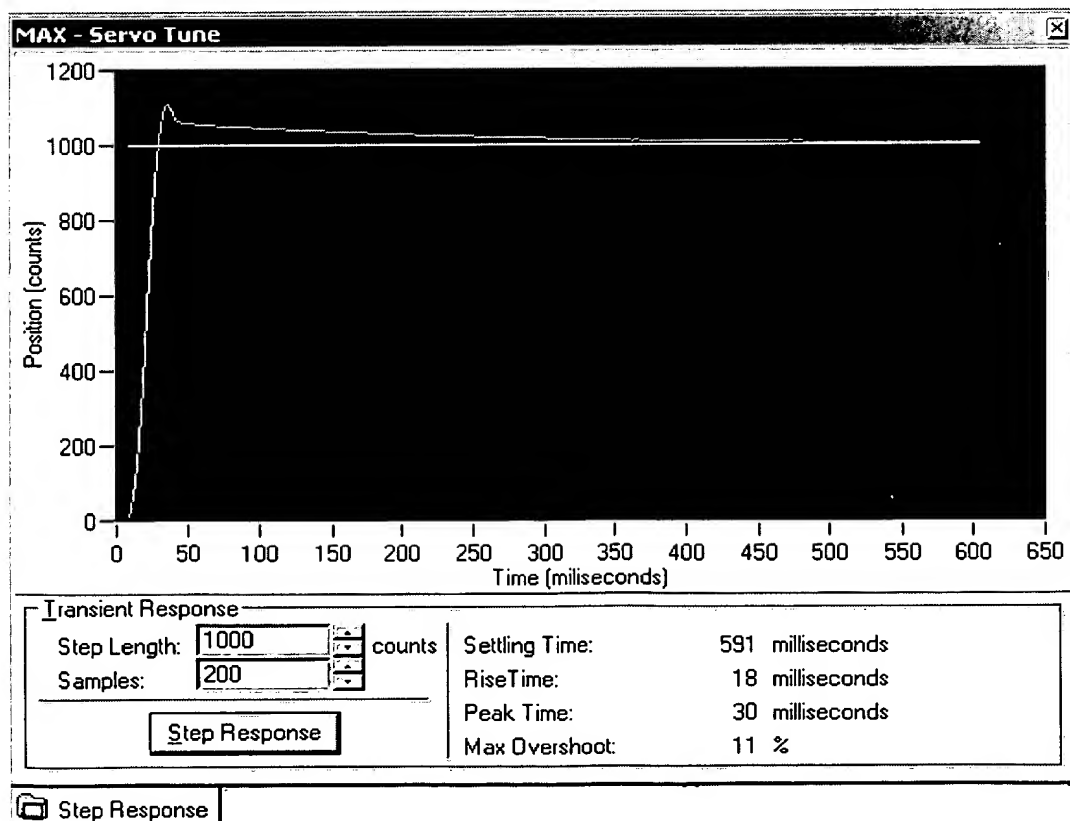


Figure 6B